



## Remote API Functions (Python)

### simxAddStatusBarMessage (regular API equivalent: simAddStatusBarMessage)

Description	Adds a message to the status bar.
Python synopsis	number errorCode=simxAddStatusBarMessage(number clientID,string message,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>message</b> : the message to display <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is simx_opmode_oneshot
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxAppendStringSignal

Description	DEPRECATED. Refer to <a href="#">simxWriteStringStream</a> instead.  Appends a string to a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a> . See also <a href="#">simxSetStringSignal</a> .
Python synopsis	number errorCode=simxAppendStringSignal(number clientID,string signalName,string signalValueToAppend,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>signalValueToAppend</b> : value to append to the signal. That value may contain any value, including embedded zeros. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is simx_opmode_oneshot
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxAuxiliaryConsoleClose (regular API equivalent: simAuxiliaryConsoleClose)

Description	Closes an auxiliary console window. See also <a href="#">simxAuxiliaryConsoleOpen</a> .
Python synopsis	number errorCode=simxAuxiliaryConsoleClose(number clientID,number consoleHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>consoleHandle</b> : the handle of the console window, previously returned by the <a href="#">simxAuxiliaryConsoleOpen</a> command <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is simx_opmode_oneshot
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxAuxiliaryConsoleOpen (regular API equivalent: simAuxiliaryConsoleOpen)

Description	Opens an auxiliary console window for text display. This console window is different from the application main console window. Console window handles are shared across all simulator scenes. See also <a href="#">simxAuxiliaryConsolePrint</a> , <a href="#">simxAuxiliaryConsoleShow</a> and <a href="#">simxAuxiliaryConsoleClose</a> .
Python synopsis	number errorCode,number consoleHandle=simxAuxiliaryConsoleOpen(number clientID,string title,number maxLines,number mode,array position,array size,array textColor,array backgroundColor,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>title</b> : the title of the console window <b>maxLines</b> : the number of text lines that can be displayed and buffered <b>mode</b> : bit-coded value. Bit0 set indicates that the console window will automatically close at simulation end, bit1 set indicates that lines will be wrapped, bit2 set indicates that the user can close the console window, bit3 set indicates that the console will automatically be hidden during simulation pause, bit4 set indicates that the console will not automatically hide when the user switches to another scene. <b>position</b> : the initial position of the console window (x and y value). Can be <b>None</b> for default values. <b>size</b> : the initial size of the console window (x and y value). Can be <b>None</b> for default values. <b>textColor</b> : the color of the text (rgb values, 0-1). Can be <b>None</b> for default values. <b>backgroundColor</b> : the background color of the console window (rgb values, 0-1). Can be <b>None</b> for default values. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is simx_opmode_oneshot_wait
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>consoleHandle</b> : the handle of the created console

Other languages [C/C++](#), [Java](#), [Matlab](#), [Octave](#), [Urbi](#)

#### simxAuxiliaryConsolePrint (regular API equivalent: [simxAuxiliaryConsolePrint](#))

Description	Prints to an auxiliary console window. See also <a href="#">simxAuxiliaryConsoleOpen</a> .
Python synopsis	number errorCode=simxAuxiliaryConsolePrint(number clientID,number consoleHandle,string txt,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>consoleHandle</b> : the handle of the console window, previously returned by the <a href="#">simxAuxiliaryConsoleOpen</a> command <b>txt</b> : the text to append, or " <b>None</b> " to clear the console window <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxAuxiliaryConsoleShow (regular API equivalent: [simxAuxiliaryConsoleShow](#))

Description	Shows or hides an auxiliary console window. See also <a href="#">simxAuxiliaryConsoleOpen</a> and <a href="#">simxAuxiliaryConsoleClose</a> .
Python synopsis	number errorCode=simxAuxiliaryConsoleShow(number clientID,number consoleHandle,number showState,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>consoleHandle</b> : the handle of the console window, previously returned by the <a href="#">simxAuxiliaryConsoleOpen</a> command <b>showState</b> : indicates whether the console should be hidden (0) or shown (!=0) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxBreakForceSensor (regular API equivalent: [simxBreakForceSensor](#))

Description	Allows breaking a force sensor during simulation. A broken force sensor will lose its positional and orientational constraints. See also <a href="#">simxReadForceSensor</a> .
Python synopsis	number errorCode=simxBreakForceSensor(number clientID,number forceSensorHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>forceSensorHandle</b> : handle of the force sensor <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxClearFloatSignal (regular API equivalent: [simxClearFloatSignal](#))

Description	Clears a float signal (removes it). See also <a href="#">simxSetFloatSignal</a> , <a href="#">simxClearIntegerSignal</a> and <a href="#">simxClearStringSignal</a> .
Python synopsis	number errorCode=simxClearFloatSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal or an empty string to clear all float signals <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxClearIntegerSignal (regular API equivalent: [simxClearIntegerSignal](#))

Description	Clears an integer signal (removes it). See also <a href="#">simxSetIntegerSignal</a> , <a href="#">simxClearFloatSignal</a> and <a href="#">simxClearStringSignal</a> .
Python synopsis	number errorCode=simxClearIntegerSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal or an empty string to clear all integer signals <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxClearStringSignal (regular API equivalent: [simxClearStringSignal](#))

Description	Clears a string signal (removes it). See also <a href="#">simxSetStringSignal</a> , <a href="#">simxClearIntegerSignal</a> and <a href="#">simxClearFloatSignal</a> .
Python synopsis	number errorCode=simxClearStringSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal or an empty string to clear all string signals <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxCloseScene (regular API equivalent: simCloseScene)**

Description	Closes current scene, and switches to another open scene. If there is no other open scene, a new scene is then created. Should only be called when simulation is not running and is only executed by <a href="#">continuous remote API server services</a> . See also <a href="#">simxLoadScene</a> .
Python synopsis	number errorCode=simxCloseScene(number clientID,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxCopyPasteObjects (regular API equivalent: simCopyPasteObjects)**

Description	Copies and pastes objects, together with all their associated calculation objects and child scripts. To copy and paste whole models, you can simply copy and paste the model base object.
Python synopsis	number errorCode,array newObjectHandles=simxCopyPasteObjects(number clientID,array objectHandles,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandles</b> : an array containing the handles of the objects to copy <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>newObjectHandles</b> : an array containing the handles of newly created objects. Individual objects of a new model are not returned, but only the model base.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxCreateBuffer (regular API equivalent: simCreateBuffer)**

Description	Creates a buffer. The buffer needs to be released with <a href="#">simxReleaseBuffer</a> except otherwise explicitly specified. This is a remote API helper function.
Python synopsis	charPointer buffer=simxCreateBuffer(number bufferSize)
Python parameters	<b>bufferSize</b> : size of the buffer in bytes
Python return values	<b>buffer</b> : the created buffer
Other languages	<a href="#">C/C++</a> , <a href="#">Matlab</a>

**simxCreateDummy (regular API equivalent: simCreateDummy)**

Description	Creates a <a href="#">dummy</a> in the scene.
Python synopsis	number errorCode,number dummyHandle=simxCreateDummy(number clientID,number size,array colors,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>size</b> : the size of the dummy. <b>colors</b> : 4*3 bytes (0-255) for ambient_diffuse RGB, 3 reserved values (set to zero), specular RGB and emissive RGB. Can be <b>None</b> for default colors. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return value	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>dummyHandle</b> : handle of the created dummy.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxDisplayDialog (regular API equivalent: simDisplayDialog)**

Description	Displays a generic dialog box during simulation (and only during simulation!). Use in conjunction with <a href="#">simxGetDialogResult</a> , <a href="#">simxGetDialogInput</a> and <a href="#">simxEndDialog</a> . Use <a href="#">custom user interfaces</a> instead if a higher customization level is required.
Python synopsis	number errorCode,number dialogHandle,number uiHandle=simxDisplayDialog(number clientID,string titleText,string mainText,number dialogType,string initialText,array titleColors,array dialogColors,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> .

	<b>titleText:</b> Title bar text <b>mainText:</b> Information text <b>dialogType:</b> a <a href="#">generic dialog style</a> <b>initialText:</b> Initial text in the edit box if the dialog is of type <code>sim_dlgstyle_input</code> . Cannot be <b>None</b> . <b>titleColors:</b> Title bar color (6 values for RGB for background and foreground). Can be <b>None</b> for default values. <b>dialogColors:</b> Dialog color (6 values for RGB for background and foreground). Can be <b>None</b> for default Values. <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>dialogHandle:</b> handle of the generic dialog (different from custom user interface handle!! (see hereafter)). This handle should be used with the following functions: <a href="#">simxGetDialogResult</a> , <a href="#">simxGetDialogInput</a> and <a href="#">simxEndDialog</a> . <b>uiHandle:</b> the handle of the corresponding custom user interface
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxEndDialog (regular API equivalent: [simEndDialog](#))

Description	Closes and releases resource from a previous call to <a href="#">simxDisplayDialog</a> . Even if the dialog is not visible anymore, you should release resources by using this function (however at the end of a simulation, all dialog resources are automatically released).
Python synopsis	<code>number errorCode=simxEndDialog(number clientID,number dialogHandle,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>dialogHandle:</b> handle of generic dialog (return value of <a href="#">simxDisplayDialog</a> ) <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxEraseFile

Description	Erases a file on the server side. This function is used by several other functions internally (e.g. <a href="#">simxLoadModel</a> ). See also <a href="#">simxTransferFile</a> . This is a remote API helper function.
Python synopsis	<code>number errorCode=simxEraseFile(number clientID,string fileName_serverSide,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>fileName_serverSide:</b> the file to erase on the server side. For now, do not specify a path (the file will be erased in the remote API plugin directory) <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxFinish

Description	Ends the communication thread. This should be the very last remote API function called on the client side. <code>simxFinish</code> should only be called after a successfull call to <a href="#">simxStart</a> . This is a remote API helper function.
Python synopsis	<code>simxFinish(number clientID)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . Can be -1 to end all running communication threads.
Python return values	none
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxGetAndClearStringSignal

Description	DEPRECATED. Refer to <a href="#">simxReadStringStream</a> instead.  Gets the value of a string signal, then clears it. Useful to retrieve continuous data from the server. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a> . See also <a href="#">simxGetStringSignal</a> .
Python synopsis	<code>number errorCode,string signalValue=simxGetAndClearStringSignal(number clientID,string signalName,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>signalName:</b> name of the signal <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Since this function will clear a read signal, and we cannot afford to wait for a reply (well, we could, but that would mean a blocking operation), the function operates in a special mode and should be used as in following example:
	<pre>'''Initialization phase:''' err,signal=vrep.simxGetAndClearStringSignal(     clientID,"sig",vrep.simx_opmode_streaming)</pre>

	<pre>'''while we are connected:''' while vrep.simxGetConnectionId(clientID) != -1:     err, signal=vrep.simxGetAndClearStringSignal(         clientID,"sig",vrep.simx_opmode_buffer)     if (err==vrep.simx_return_ok):         '''A signal was retrieved.'''         '''Enable streaming again (was automatically disabled with the positive event):'''         err, signal=vrep.simxGetAndClearStringSignal(             clientID,"sig",vrep.simx_opmode_streaming)     ..</pre>
Python return values	<b>errorCode:</b> a remote API function return code <b>signalValue:</b> the value of the signal.
Other languages	C/C++, Java, Matlab, Octave, Urbi

#### simxGetArrayParameter (regular API equivalent: simGetArrayParameter)

Description	Retrieves 3 values from an array. See the <a href="#">array parameter identifiers</a> . See also <a href="#">simxSetArrayParameter</a> , <a href="#">simxGetBooleanParameter</a> , <a href="#">simxGetIntegerParameter</a> , <a href="#">simxGetFloatingParameter</a> and <a href="#">simxGetStringParameter</a> .
Python synopsis	number errorCode,array paramValues=simxGetArrayParameter(number clientID,number paramIdentifier,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier:</b> an <a href="#">array parameter identifier</a> <b>operationMode:</b> a remote API function operation mode. Recommended operation mode for this function is <code>simx_opmode_one-shot_wait</code> (if not called on a regular basis)
Python return values	<b>errorCode:</b> a remote API function return code <b>paramValues:</b> an array containing 3 values
Other languages	C/C++, Java, Matlab, Octave, Urbi

#### simxGetBooleanParameter (regular API equivalent: simGetBooleanParameter)

Description	Retrieves a boolean value. See the <a href="#">Boolean parameter identifiers</a> . See also <a href="#">simxSetBooleanParameter</a> , <a href="#">simxGetIntegerParameter</a> , <a href="#">simxGetFloatingParameter</a> , <a href="#">simxGetArrayParameter</a> and <a href="#">simxGetStringParameter</a> .
Python synopsis	number errorCode,boolean paramValue=simxGetBooleanParameter(number clientID,number paramIdentifier,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier:</b> a <a href="#">Boolean parameter identifier</a> <b>operationMode:</b> a remote API function operation mode. Recommended operation mode for this function is <code>simx_opmode_one-shot_wait</code> (if not called on a regular basis)
Python return values	<b>errorCode:</b> a remote API function return code <b>paramValue:</b> the boolean value
Other languages	C/C++, Java, Matlab, Octave, Urbi

#### simxGetCollisionHandle (regular API equivalent: simGetCollisionHandle)

Description	Retrieves a collision object handle based on its name. If the client application is launched from a <a href="#">child script</a> , then you could also let the child script figure out what handle correspond to what collision object, and send the handles as additional arguments to the client application during its launch. See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number handle=simxGetCollisionHandle(number clientID,string collisionObjectName,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>collisionObjectName:</b> name of the collision object. If possible, don't rely on the <a href="#">automatic name adjustment mechanism</a> , and always specify the full collision object name, including the #: if the collision object is "myCollision", specify "myCollision#", if the collision object is "myCollision#0", specify "myCollision#0", etc. <b>operationMode:</b> a remote API function operation mode. Recommended operation mode for this function is <code>simx_opmode_one-shot_wait</code>
Python return values	<b>errorCode:</b> a remote API function return code <b>handle:</b> the collision handle
Other languages	C/C++, Java, Matlab, Octave, Urbi

#### simxGetConnectionId

Description	Returns the ID of the current connection. Use this function to track the connection state to the server. See also <a href="#">simxStart</a> . This is a remote API helper function.
Python synopsis	number connectionId=simxGetConnectionId(number clientID)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> .
Python return values	<b>connectionId:</b> a connection ID, or -1 if the client is not connected to the server. Different connection IDs indicate temporary disconnections in-between.

Other languages [C/C++](#), [Java](#), [Matlab](#), [Octave](#), [Urbi](#)

#### simxGetDialogInput (regular API equivalent: [simGetDialogInput](#))

Description	Queries the text the user entered into a generic dialog box of style <code>sim_dlgstyle_input</code> . To be used after <a href="#">simxDisplayDialog</a> was called and after <a href="#">simxGetDialogResult</a> returned <code>sim_dlgret_ok</code> .
Python synopsis	<code>number errorCode,string inputText=simxGetDialogInput(number clientID,number dialogHandle,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>dialogHandle</b> : handle of generic dialog (return value of <a href="#">simxDisplayDialog</a> ) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>inputText</b> : the string the user entered.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetDialogResult (regular API equivalent: [simGetDialogResult](#))

Description	Queries the result of a dialog box. To be used after <a href="#">simxDisplayDialog</a> was called.
Python synopsis	<code>number errorCode,number result=simxGetDialogResult(number clientID,number dialogHandle,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>dialogHandle</b> : handle of generic dialog (return value of <a href="#">simxDisplayDialog</a> ) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>result</b> : the <a href="#">result value</a> .  Note. If the result is <code>sim_dlgret_still_open</code> , the dialog was not closed and no button was pressed. Otherwise, you should free resources with <a href="#">simxEndDialog</a> (the dialog might not be visible anymore, but is still present)
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetDistanceHandle (regular API equivalent: [simGetDistanceHandle](#))

Description	Retrieves a distance object handle based on its name. If the client application is launched from a <a href="#">child script</a> , then you could also let the child script figure out what handle correspond to what distance object, and send the handles as additional arguments to the client application during its launch. See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,number handle=simxGetDistanceHandle(number clientID,string distanceObjectName,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>distanceObjectName</b> : name of the distance object. If possible, don't rely on the <a href="#">automatic name adjustment mechanism</a> , and always specify the full distance object name, including the #: if the distance object is "myDistance", specify "myDistance#", if the distance object is "myDistance#0", specify "myDistance#0", etc. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>handle</b> : handle of the distance object
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetFloatingParameter (regular API equivalent: [simGetFloatingParameter](#))

Description	Retrieves a floating point value. See the <a href="#">floating-point parameter identifiers</a> . See also <a href="#">simxSetFloatingParameter</a> , <a href="#">simxGetBooleanParameter</a> , <a href="#">simxGetIntegerParameter</a> , <a href="#">simxGetArrayParameter</a> and <a href="#">simxGetStringParameter</a> .
Python synopsis	<code>number errorCode,number paramValue=simxGetFloatingParameter(number clientID,number paramIdentifier,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : a <a href="#">floating parameter identifier</a> <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code> (if not called on a regular basis)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>paramValue</b> : a pointer that will receive the parameter value
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetFloatSignal (regular API equivalent: [simGetFloatSignal](#))

Description	Gets the value of a float signal. Signals are cleared at simulation start. See also <a href="#">simxSetFloatSignal</a> , <a href="#">simxClearFloatSignal</a> , <a href="#">simxGetIntegerSignal</a> and <a href="#">simxGetStringSignal</a> .
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Python synopsis	number errorCode,number signalValue=simxGetFloatSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>signalValue</b> : the value of the signal
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetInMessageInfo**

Description	Retrieves information about the last received message from the server. This is a remote API helper function. See also <a href="#">simxGetOutMessageInfo</a> .  If the client didn't receive any command reply from the server for a while, the data retrieved with this function won't be up-to-date. In order to avoid this, you should start at least one streaming command, which will guarantee regular message income.
Python synopsis	number result,number info=simxGetInMessageInfo(number clientID,number infoType)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>infoType</b> : an <a href="#">inbox message info type</a>
Python return values	<b>result</b> : -1 in case of an error <b>info</b> : the requested information
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetIntegerParameter (regular API equivalent: [simGetIntegerParameter](#))**

Description	Retrieves an integer value. See the <a href="#">integer parameter identifiers</a> . See also <a href="#">simxSetIntegerParameter</a> , <a href="#">simxGetBooleanParameter</a> , <a href="#">simxGetFloatingParameter</a> , <a href="#">simxGetArrayParameter</a> and <a href="#">simxGetStringParameter</a> .
Python synopsis	number errorCode,number paramValue=simxGetIntegerParameter(number clientID,number paramIdentifier,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : an <a href="#">integer parameter identifier</a> <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code> (if not called on a regular basis)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>paramValue</b> : the parameter value
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetIntegerSignal (regular API equivalent: [simGetIntegerSignal](#))**

Description	Gets the value of an integer signal. Signals are cleared at simulation start. See also <a href="#">simxSetIntegerSignal</a> , <a href="#">simxClearIntegerSignal</a> , <a href="#">simxGetFloatSignal</a> and <a href="#">simxGetStringSignal</a> .
Python synopsis	number errorCode,number signalValue=simxGetIntegerSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>signalValue</b> : the value of the signal
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetJointForce (regular API equivalent: [simGetJointForce](#))**

Description	Retrieves the force or torque applied to a joint along/about its active axis. This function retrieves meaningful information only if the joint is prismatic or revolute, and is dynamically enabled. With the <a href="#">Bullet</a> engine, this function returns the force or torque applied to the joint motor (torques from joint limits are not taken into account). With the <a href="#">ODE</a> or <a href="#">Vortex</a> engine, this function returns the total force or torque applied to a joint along/about its z-axis. See also <a href="#">simxSetJointForce</a> , <a href="#">simxReadForceSensor</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number force=simxGetJointForce(number clientID,number jointHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>force</b> : the force or the torque applied to the joint along/about its z-axis
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetJointMatrix (regular API equivalent: [simxGetJointMatrix](#))**

Description	Retrieves the intrinsic transformation matrix of a joint (the transformation caused by the joint movement). See also <a href="#">simxSetSphericalJointMatrix</a> .
Python synopsis	number errorCode,array matrix=simxGetJointMatrix(number clientID,number jointHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>matrix</b> : array containing 12 values. See the regular API equivalent function for details
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetJointPosition (regular API equivalent: [simxGetJointPosition](#))**

Description	Retrieves the intrinsic position of a joint. This function cannot be used with spherical joints (use <a href="#">simxGetJointMatrix</a> instead). See also <a href="#">simxSetJointPosition</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number position=simxGetJointPosition(number clientID,number jointHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>position</b> : intrinsic position of the joint. This is a one-dimensional value: if the joint is revolute, the rotation angle is returned, if the joint is prismatic, the translation amount is returned, etc.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetLastCmdTime**

Description	Retrieves the simulation time of the last fetched command (i.e. when the last fetched command was processed on the server side). The function can be used to verify how "fresh" a command reply is, or whether a command reply was recently updated. For example:  <pre>data=vrep.simxGetVisionSensorImage(clientID,handle,0,vrep.simx_opmode_buffer) if data[0] == vrep.simx_return_ok :     imageAcquisitionTime=vrep.simxGetLastCmdTime(clientID)</pre> <p>This is a remote API helper function.</p>
Python synopsis	number cmdTime=simxGetLastCmdTime(number clientID)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> .
Python return values	<b>cmdTime</b> : the simulation time in milliseconds when the command reply was generated, or 0 if simulation was not running.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetLastErrors (regular API equivalent: [simxGetLastError](#))**

Description	Retrieves the last 50 errors that occurred on the server side, and clears the error buffer there. Only errors that occurred because of this client will be reported.
Python synopsis	number errorCode,array errorStrings=simxGetLastErrors(number clientID,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls) when not debugging. For debugging purposes, use <code>simx_opmode_oneshot_wait</code> .
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>errorStrings</b> : the error strings
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetModelProperty (regular API equivalent: [simxGetModelProperty](#))**

Description	Retrieves the properties of a model. See also <a href="#">simxSetModelProperty</a> .
Python synopsis	number errorCode,number prop=simxGetModelProperty(number clientID,number objectHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_oneshot_wait</code> (depending on the intended usage)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>



	<b>prop</b> : the <a href="#">model property value</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxGetObjectChild (regular API equivalent: [simGetObjectChild](#))

Description	Retrieves the handle of an object's child object. See also <a href="#">simxGetObjectParent</a> .
Python synopsis	number errorCode,number childObjectHandle=simxGetObjectChild(number clientID,number parentObjectHandle,number childIndex,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>parentObjectHandle</b> : handle of the object <b>childIndex</b> : zero-based index of the child's position. To retrieve all children of an object, call the function by increasing the index until the child handle is -1 <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>childObjectHandle</b> : the handle of the child object. If the value is -1, there is no child at the given index
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxGetObjectFloatParameter (regular API equivalent: [simGetObjectFloatParameter](#))

Description	Retrieves a floating-point parameter of a object. See also <a href="#">simxSetObjectFloatParameter</a> and <a href="#">simxGetObjectIntParameter</a> .
Python synopsis	number errorCode,number parameterValue=simxGetObjectFloatParameter(number clientID,number objectHandle,number parameterID,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>parameterID</b> : identifier of the parameter to retrieve. See the <a href="#">list of all possible object parameter identifiers</a> <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_oneshot_wait</code> (depending on the intended usage)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>parameterValue</b> : the value of the parameter
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxGetObjectGroupData

Description	Simultaneously retrieves data of various objects in a V-REP scene.
Python synopsis	number errorCode,array handles,array intData,array floatData,array stringData=simxGetObjectGroupData(number clientID,number objectType,number dataType,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectType</b> : a <a href="#">scene object type</a> , or <code>sim_appobj_object_type</code> for all <a href="#">scene objects</a> . <b>dataType</b> : the type of data that is desired: 0: retrieves the object names (in <code>stringData</code> .) 1: retrieves the <a href="#">object types</a> (in <code>intData</code> ) 2: retrieves the parent object handles (in <code>intData</code> ) 3: retrieves the absolute object positions (in <code>floatData</code> . There are 3 values for each object (x,y,z)) 4: retrieves the local object positions (in <code>floatData</code> . There are 3 values for each object (x,y,z)) 5: retrieves the absolute object orientations as <a href="#">Euler angles</a> (in <code>floatData</code> . There are 3 values for each object (alpha,beta,gamma)) 6: retrieves the local object orientations as <a href="#">Euler angles</a> (in <code>floatData</code> . There are 3 values for each object (alpha,beta,gamma)) 7: retrieves the absolute object orientations as quaternions (in <code>floatData</code> . There are 4 values for each object (qx,qy,qz,qw)) 8: retrieves the local object orientations as quaternions (in <code>floatData</code> . There are 4 values for each object (qx,qy,qz,qw)) 9: retrieves the absolute object positions and orientations (as <a href="#">Euler angles</a> ) (in <code>floatData</code> . There are 6 values for each object (x,y,z,alpha,beta,gamma)) 10: retrieves the local object positions and orientations (as <a href="#">Euler angles</a> ) (in <code>floatData</code> . There are 6 values for each object (x,y,z,alpha,beta,gamma)) 11: retrieves the absolute object positions and orientations (as quaternions) (in <code>floatData</code> . There are 7 values for each object (x,y,z,qx,qy,qz,qw)) 12: retrieves the local object positions and orientations (as quaternions) (in <code>floatData</code> . There are 7 values for each object (x,y,z,qx,qy,qz,qw)) 13: retrieves proximity sensor data (in <code>intData</code> (2 values): detection state, detected object handle. In <code>floatData</code> (6 values): detected point (x,y,z) and detected surface normal (nx,ny,nz)) 14: retrieves force sensor data (in <code>intData</code> (1 values): force sensor state. In <code>floatData</code> (6 values): force (fx,fy,fz) and torque (tx,ty,tz)) 15: retrieves joint state data (in <code>floatData</code> (2 values): position, force/torque) 16: retrieves joint properties data (in <code>intData</code> (2 values): joint type, joint mode (bit16=hybrid operation). In <code>floatData</code> (2 values): joint limit low, joint range (-1.0 if joint is cyclic)) 17: retrieves the object linear velocity (in <code>floatData</code> . There are 3 values for each object

	<p>(vx,vy,vz))</p> <p>18: retrieves the object angular velocity as <a href="#">Euler angles</a> per seconds (in floatData. There are 3 values for each object (dAlpha,dBeta,dGamma))</p> <p>19: retrieves the object linear and angular velocity (in floatData. There are 6 values for each object (vx,vy,vz,dAlpha,dBeta,dGamma))</p> <p><b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation mode for this function is <code>simx_opmode_one-shot_wait</code> or <code>simx_opmode_streaming</code>.</p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a></p> <p><b>handles:</b> the object handles.</p> <p><b>intData:</b> the integer values.</p> <p><b>floatData:</b> the float values.</p> <p><b>stringData:</b> the string values.</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetObjectHandle (regular API equivalent: [simGetObjectHandle](#))

Description	Retrieves an object handle based on its name. If the client application is launched from a <a href="#">child script</a> , then you could also let the child script figure out what handle correspond to what objects, and send the handles as additional arguments to the client application during its launch. See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number handle=simxGetObjectHandle(number clientID,string objectName,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>objectName:</b> name of the object. If possible, don't rely on the <a href="#">automatic name adjustment mechanism</a>, and always specify the full object name, including the #: if the object is "myJoint", specify "myJoint#", if the object is "myJoint#0", specify "myJoint#0", etc.</p> <p><b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation mode for this function is <code>simx_opmode_one-shot_wait</code></p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a></p> <p><b>handle:</b> the handle</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetObjectIntParameter (regular API equivalent: [simGetObjectIntParameter](#))

Description	Retrieves an integer parameter of a object. See also <a href="#">simxSetObjectIntParameter</a> and <a href="#">simxGetObjectFloatParameter</a> .
Python synopsis	number errorCode,number parameterValue=simxGetObjectIntParameter(number clientID,number objectHandle,number parameterID,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>objectHandle:</b> handle of the object</p> <p><b>parameterID:</b> identifier of the parameter to retrieve. See the <a href="#">list of all possible object parameter identifiers</a></p> <p><b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_one-shot_wait</code> (depending on the intended usage)</p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a></p> <p><b>parameterValue:</b> the value of the parameter</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetObjectOrientation (regular API equivalent: [simGetObjectOrientation](#))

Description	Retrieves the orientation ( <a href="#">Euler angles</a> ) of an object. See also <a href="#">simxSetObjectOrientation</a> , <a href="#">simxGetObjectPosition</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,array eulerAngles=simxGetObjectOrientation(number clientID,number objectHandle,number relativeToObjectHandle,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>objectHandle:</b> handle of the object</p> <p><b>relativeToObjectHandle:</b> indicates relative to which reference frame we want the orientation. Specify -1 to retrieve the absolute orientation, <code>sim_handle_parent</code> to retrieve the orientation relative to the object's parent, or an object handle relative to whose reference frame you want the orientation</p> <p><b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)</p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a></p> <p><b>eulerAngles:</b> the Euler angles (alpha, beta and gamma)</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetObjectParent (regular API equivalent: [simGetObjectParent](#))

Description	Retrieves the handle of an object's parent object. See also <a href="#">simxGetObjectChild</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number parentObjectHandle=simxGetObjectParent(number clientID,number objectHandle,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> .

	<b>objectHandle</b> : handle of the object <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>parentObjectHandle</b> : the handle of the parent object. If the value is -1, the object has no parent
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetObjectPosition (regular API equivalent: [simGetObjectPosition](#))**

Description	Retrieves the position of an object. See also <a href="#">simxSetObjectPosition</a> , <a href="#">simxGetObjectOrientation</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,array position=simxGetObjectPosition(number clientID,number objectHandle,number relativeToObjectHandle,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>relativeToObjectHandle</b> : indicates relative to which reference frame we want the position. Specify -1 to retrieve the absolute position, <code>sim_handle_parent</code> to retrieve the position relative to the object's parent, or an object handle relative to whose reference frame you want the position <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>position</b> : the position (x,y,z)
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetObjects (regular API equivalent: [simGetObjects](#))**

Description	Retrieves object handles of a given type, or of all types (i.e. all object handles). See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,array objectHandles=simxGetObjects(number clientID,number objectType,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectType</b> : <a href="#">object type</a> ( <code>sim_object_shape_type</code> , <code>sim_object_joint_type</code> , etc., or <code>sim_handle_all</code> for any type of object) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>objectHandles</b> : an object handle array.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetObjectSelection (regular API equivalent: [simGetObjectSelection](#))**

Description	Retrieves all selected object's handles. See also <a href="#">simxSetObjectSelection</a> .
Python synopsis	<code>number errorCode,array objectHandles=simxGetObjectSelection(number clientID,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_oneshot_wait</code> depending on the intent.
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>objectHandles</b> : an object handle array.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetObjectVelocity (regular API equivalent: [simGetObjectVelocity](#))**

Description	Retrieves the linear and angular velocity of an object. See also <a href="#">simxGetObjectPosition</a> , <a href="#">simxGetObjectOrientation</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,array linearVelocity,array angularVelocity=simxGetObjectVelocity(number clientID,number objectHandle,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>linearVelocity</b> : the linear velocity (vx, vy, vz) <b>angularVelocity</b> : the angular velocity (dAlpha, dBeta, dGamma)
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetOutMessageInfo**

Description	Retrieves information about the next message to send to the server. This is a remote API helper function. See also <a href="#">simxGetInMessageInfo</a> .
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Python synopsis	number result,number info=simxGetOutMessageInfo(number clientID,number infoType)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>infoType</b> : an <a href="#">outbox message info type</a>
Python return values	<b>result</b> : -1 in case of an error <b>info</b> : the requested information
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetPingTime**

Description	Retrieves the time needed for a command to be sent to the server, executed, and sent back. That time depends on various factors like the client settings, the network load, whether a simulation is running, whether the simulation is real-time, the simulation time step, etc. The function is blocking. This is a remote API helper function.
Python synopsis	number errorCode,number pingTime=simxGetPingTime(number clientID)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> .
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>pingTime</b> : a pointer to a <a href="#">simxInt</a> value accepting the ping time in milliseconds.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetStringParameter (regular API equivalent: [simGetStringParameter](#))**

Description	Retrieves a string value. See the <a href="#">string parameter identifiers</a> . See also <a href="#">simxGetBooleanParameter</a> , <a href="#">simxGetIntegerParameter</a> , <a href="#">simxGetArrayParameter</a> and <a href="#">simxGetFloatingParameter</a> .
Python synopsis	number errorCode,string paramValue=simxGetStringParameter(number clientID,number paramIdentifier,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : a <a href="#">string parameter identifier</a> <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <a href="#">simx_opmode_oneshot_wait</a> (if not called on a regular basis)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>paramValue</b> : the string.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetStringSignal (regular API equivalent: [simGetStringSignal](#))**

Description	Gets the value of a string signal. Signals are cleared at simulation start. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a> . See also <a href="#">simxSetStringSignal</a> , <a href="#">simxGetAndClearStringSignal</a> , <a href="#">simxClearStringSignal</a> , <a href="#">simxGetIntegerSignal</a> and <a href="#">simxGetFloatSignal</a> .
Python synopsis	number errorCode,string signalValue=simxGetStringSignal(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <a href="#">simx_opmode_streaming</a> (the first call) and <a href="#">simx_opmode_buffer</a> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>signalValue</b> : the value of the signal.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetUIButtonProperty (regular API equivalent: [simGetUIButtonProperty](#))**

Description	Retrieves the properties of a custom user interface button. See also <a href="#">simxSetUIButtonProperty</a> .
Python synopsis	number errorCode,number prop=simxGetUIButtonProperty(number clientID,number uiHandle,number uiButtonID,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiHandle</b> : handle of the custom user interface <b>uiButtonID</b> : handle (or id) of the custom user interface button <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <a href="#">simx_opmode_streaming</a> (the first call) and <a href="#">simx_opmode_buffer</a> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>prop</b> : a <a href="#">button property value</a> .
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetUIEventButton (regular API equivalent: [simGetUIEventButton](#))**

Description	Gets the button handle (i.e. ID) and some auxiliary values of the last occurred event in that custom user interface. The function will then clear the event. When a custom user interface button is pressed, a slider is moved or an edit box is changed, an event is registered and stored in the custom user interface.
Python synopsis	number errorCode,number uiEventButtonID,array auxValues=simxGetUIEventButton(number clientID,number uiHandle,number operationMode)

Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.  <b>uiHandle:</b> handle of the custom user interface  <b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Since this function will clear a read event, and we cannot afford to wait for a reply (well, we could, but that would mean a blocking operation), the function operates in a special mode and should be used as in following example:</p> <pre>'''Initialization phase:''' uiHandle = -1 err,uiHandle=vrep.simxGetUIHandle(clientID,"UI",vrep.simx_opmode_oneshot_wait) buttonEventID = -1 err,buttonEventID,aux=vrep.simxGetUIEventButton(     clientID,uiHandle,vrep.simx_opmode_streaming)  '''while we are connected:''' while vrep.simxGetConnectionId(clientID) != -1:     err,buttonEventID,aux=vrep.simxGetUIEventButton(         clientID,uiHandle,vrep.simx_opmode_buffer)     if ((err==vrep.simx_return_ok) &amp;&amp; (buttonEventID!=-1)):         '''A button was pressed/edited/changed. React to it here!'''         '''Enable streaming again (was automatically disabled with the positive event):'''         err,buttonEventID,aux=vrep.simxGetUIEventButton(             clientID,uiHandle,vrep.simx_opmode_streaming)      ..</pre>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a>  <b>uiEventButtonID:</b> id of the UI button where an event occurred, or -1 if no event occurred  <b>auxValues:</b> 2 values:              value1: the <a href="#">button property</a>              value2: for sliders: slider state (0-1000), for stay down buttons: down state (0 or 1), for up/down event buttons: up/down events (0 or 1)</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetUIHandle (regular API equivalent: [simGetUIHandle](#))

Description	Retrieves the handle of a custom user interface. If the client application is launched from a <a href="#">child script</a> , then you could also let the child script figure out what handle correspond to what UIs, and send the handles as additional arguments to the client application during its launch. See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number handle=simxGetUIHandle(number clientID,string uiName,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.  <b>uiName:</b> name of the UI. If possible, don't rely on the <a href="#">automatic name adjustment mechanism</a>, and always specify the full object name, including the #: if the UI is "myUI", specify "myUI#", if the UI is "myUI#0", specify "myUI#0", etc.  <b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code></p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a>  <b>handle:</b> the handle</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetUISlider (regular API equivalent: [simGetUISlider](#))

Description	Gets the slider position of a custom user interface button (must be slider-type button). See also <a href="#">simxSetUISlider</a> .
Python synopsis	number errorCode,number position=simxGetUISlider(number clientID,number uiHandle,number uiButtonID,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.  <b>uiHandle:</b> handle of the custom user interface  <b>uiButtonID:</b> handle of a button inside the specified custom user interface  <b>operationMode:</b> a <a href="#">remote API function operation mode</a>. Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)</p>
Python return values	<p><b>errorCode:</b> a <a href="#">remote API function return code</a>  <b>position:</b> the slider position (value between 0 and 1000)</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxGetVisionSensorDepthBuffer (regular API equivalent: [simGetVisionSensorDepthBuffer](#))

Description	Retrieves the depth buffer of a vision sensor. The returned data doesn't make sense if <a href="#">simHandleVisionSensor</a> wasn't called previously ( <code>simHandleVisionSensor</code> is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the <a href="#">simxGetLastCmdTime</a> function to verify the "freshness" of the retrieved data. See also <a href="#">simxGetVisionSensorImage</a> .
Python synopsis	number errorCode,array resolution,array buffer=simxGetVisionSensorDepthBuffer(number clientID,number sensorHandle,number operationMode)
Python parameters	<p><b>clientID:</b> the client ID. refer to <a href="#">simxStart</a>.  <b>sensorHandle:</b> handle of the vision sensor</p>

	<b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>resolution:</b> the resolution of the image (x, y) <b>buffer:</b> the depth buffer data. Values are in the range of 0-1 (0=closest to sensor, 1=farthest from sensor).
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxGetVisionSensorImage (regular API equivalent: [simxGetVisionSensorImage](#))**

Description	Retrieves the image of a vision sensor. The returned data doesn't make sense if <a href="#">simHandleVisionSensor</a> wasn't called previously ( <code>simHandleVisionSensor</code> is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the <a href="#">simxGetLastCmdTime</a> function to verify the "freshness" of the retrieved data. See also <a href="#">simxSetVisionSensorImage</a> , <a href="#">simxGetVisionSensorDepthBuffer</a> and <a href="#">simxReadVisionSensor</a> .
Python synopsis	<code>number errorCode,array resolution,array image=simxGetVisionSensorImage(number clientID,number sensorHandle,number options,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>sensorHandle:</b> handle of the vision sensor <b>options:</b> image options, bit-coded: bit0 set: each image pixel is a byte (greyscale image), otherwise each image pixel is a rgb byte-triplet <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>resolution:</b> the resolution of the image (x,y) <b>image:</b> the image data.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxJointGetForce (DEPRECATED)**

Description	DEPRECATED. See <a href="#">simxGetJointForce</a> instead.
Python synopsis	<code>number errorCode,number force=simxJointGetForce(number clientID,number jointHandle,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle:</b> handle of the joint <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>force:</b> the force or the torque applied to the joint along/about its z-axis
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxLoadModel (regular API equivalent: [simxLoadModel](#))**

Description	Loads a previously saved model. See also <a href="#">simxLoadUI</a> , <a href="#">simxLoadScene</a> and <a href="#">simxTransferFile</a> .
Python synopsis	<code>number errorCode,number baseHandle=simxLoadModel(number clientID,string modelPathAndName,number options,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>modelPathAndName:</b> the model filename, including the path and extension (".ttm"). The file is relative to the client or server system depending on the <b>options</b> value (see next argument) <b>options:</b> options, bit-coded: bit0 set: the specified file is located on the client side (in that case the function will be blocking since the model first has to be transferred to the server). Otherwise it is located on the server side <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>baseHandle:</b> the loaded model base.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxLoadScene (regular API equivalent: [simxLoadScene](#))**

Description	Loads a previously saved scene. Should only be called when simulation is not running and is only executed by <a href="#">continuous remote API server services</a> . See also <a href="#">simxCloseScene</a> , <a href="#">simxLoadModel</a> , <a href="#">simxLoadUI</a> and <a href="#">simxTransferFile</a> .
Python synopsis	<code>number errorCode=simxLoadScene(number clientID,string scenePathAndName,number options,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>scenePathAndName:</b> the scene filename, including the path and extension (".tts"). The file is relative to the client or server system depending on the <b>options</b> value (see next argument) <b>options:</b> options, bit-coded: bit0 set: the specified file is located on the client side (in that case the function will be blocking since the scene first has to be transferred to the server). Otherwise it is located on

	the server side <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxLoadUI (regular API equivalent: [simLoadUI](#))**

Description	Loads previously saved custom user interfaces. See also <a href="#">simxLoadModel</a> , <a href="#">simxLoadScene</a> and <a href="#">simxTransferFile</a> .
Python synopsis	<code>number errorCode,array uiHandles=simxLoadUI(number clientID,string uiPathAndName,number options,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiPathAndName</b> : the ui filename, including the path and extension ("ttb"). The file is relative to the client or server system depending on the <b>options</b> value (see next argument) <b>options</b> : options, bit-coded: bit0 set: the specified file is located on the client side (in that case the function will be blocking since the UI file first has to be transferred to the server). Otherwise it is located on the server side <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>uiHandles</b> : the loaded UI handles.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxPackFloats**

Description	Packs an array of floats into a string. This is a remote API helper function. See also <a href="#">simxUnpackFloats</a> and <a href="#">simxPackInts</a> .
Python synopsis	<code>string packedData=simxPackFloats(array floatValues)</code>
Python parameters	<b>floatValues</b> : an array of numbers we wish to pack as floats
Python return values	<b>packedData</b> : a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Other languages	<a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxPackInts**

Description	Packs an array of integers into a string. This is a remote API helper function. See also <a href="#">simxUnpackInts</a> and <a href="#">simxPackFloats</a> .
Python synopsis	<code>string packedData=simxPackInts(array intValue)</code>
Python parameters	<b>intValues</b> : an array of numbers we wish to pack as integers
Python return values	<b>packedData</b> : a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Other languages	<a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxPauseCommunication**

Description	Allows to temporarily halt the communication thread from sending data. This can be useful if you need to send several values to V-REP that should be received and evaluated at the same time. This is a remote API helper function.
Python synopsis	<code>number errorCode=simxPauseCommunication(number clientID,boolean pause)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>pause</b> : whether the communication thread should pause or run normally.  Usage example:  <pre>vrep.simxPauseCommunication(clientID,True) vrep.simxSetJointPosition(clientID, joint1Handle, joint1Value, vrep.simx_opmode_oneshot) vrep.simxSetJointPosition(clientID, joint2Handle, joint2Value, vrep.simx_opmode_oneshot) vrep.simxSetJointPosition(clientID, joint3Handle, joint3Value, vrep.simx_opmode_oneshot) vrep.simxPauseCommunication(clientID, False)  '''Above's 3 joints will be received and set on the V-REP side at the same time'''</pre>
Python return values	<b>errorCode</b> : 0 in case of operation success.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxPauseSimulation (regular API equivalent: [simPauseSimulation](#))**

Description	Requests a pause of a simulation. See also <a href="#">simxStartSimulation</a> and <a href="#">simxStopSimulation</a> .
Python synopsis	<code>number errorCode=simxPauseSimulation(number clientID,number operationMode)</code>
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this

	function is <code>simx_opmode_oneshot</code> .
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxQuery**

Description	<p>Sends a query string to V-REP, and waits for a reply string. Query and reply strings can be accessed via string signals. This function allows for instance to have a <a href="#">child script</a>, another remote API client or a <a href="#">ROS node</a> handle special requests coming from this remote API client, then send a reply back. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a>, <a href="#">simxPackFloats</a>, <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a>.</p> <p>Usage example where a child script handles a request:</p> <pre># Following is the remote API client side: res,replyData=vrep.simxQuery(clientID,'request','send me a 42','reply',5000) if res==vrep.simx_return_ok:     print "The reply is: %s" % replyData</pre> <pre>-- This is the child script side. The child script is non-threaded and -- following part executed at each simulation pass: req=simGetStringSignal("request") if (req) then     simClearStringSignal("request")     if (req=="send me a 42") then         simSetStringSignal("reply","42\0") -- will be automatically cleared by the client     end end</pre>
Python synopsis	<code>number errorCode,string retSignalValue=simxQuery(number clientID,string signalName,string signalValue,string retSignalName,number timeOutInMs)</code>
Python parameters	<p><b>clientID</b>: the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>signalName</b>: name of the signal that contains the request string</p> <p><b>signalValue</b>: the request string.</p> <p><b>retSignalName</b>: name of the signal that contains the reply string</p> <p><b>timeOutInMs</b>: the maximum time in milliseconds that the function will wait for a reply.</p>
Python return value	<p><b>errorCode</b>: a <a href="#">remote API function return code</a></p> <p><b>retSignalValue</b>: the reply string</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxReadCollision (regular API equivalent: [simReadCollision](#))**

Description	Reads the collision state of a registered collision object. This function doesn't perform collision detection, it merely reads the result from a previous call to <a href="#">simHandleCollision</a> ( <code>simHandleCollision</code> is called in the default main script). See also <a href="#">simGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,boolean collisionState=simxReadCollision(number clientID,number collisionObjectHandle,number operationMode)</code>
Python parameters	<p><b>clientID</b>: the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>collisionObjectHandle</b>: handle of the collision object</p> <p><b>operationMode</b>: a <a href="#">remote API function operation mode</a>. Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)</p>
Python return values	<p><b>errorCode</b>: a <a href="#">remote API function return code</a></p> <p><b>collisionState</b>: the collision state</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxReadDistance (regular API equivalent: [simReadDistance](#))**

Description	Reads the distance that a registered distance object measured. This function doesn't perform minimum distance calculation, it merely reads the result from a previous call to <a href="#">simHandleDistance</a> ( <code>simHandleDistance</code> is called in the default main script). See also <a href="#">simGetObjectGroupData</a> .
Python synopsis	<code>number errorCode,number minimumDistance=simxReadDistance(number clientID,number distanceObjectHandle, number operationMode)</code>
Python parameters	<p><b>clientID</b>: the client ID. refer to <a href="#">simxStart</a>.</p> <p><b>distanceObjectHandle</b>: handle of the distance object</p> <p><b>operationMode</b>: a <a href="#">remote API function operation mode</a>. Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)</p>
Python return values	<p><b>errorCode</b>: a <a href="#">remote API function return code</a></p> <p><b>minimumDistance</b>: the minimum distance</p>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxReadForceSensor (regular API equivalent: [simReadForceSensor](#))**



Description	Reads the force and torque applied to a force sensor (filtered values are read), and its current state ('unbroken' or 'broken'). See also <a href="#">simxBreakForceSensor</a> , <a href="#">simxGetJointForce</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,number state,array forceVector,array torqueVector=simxReadForceSensor(number clientID,number forceSensorHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>forceSensorHandle</b> : handle of the force sensor <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>state</b> : the state of the force sensor bit 0 set: force and torque data is available, otherwise it is not (yet) available (e.g. when not enough values are present for the filter) bit 1 set: force sensor is broken, otherwise it is still intact ('unbroken') <b>forceVector</b> : the force vector (x,y,z) <b>torqueVector</b> : the torque vector (x,y,z)
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxReadProximitySensor (regular API equivalent: [simReadProximitySensor](#))

Description	Reads the state of a proximity sensor. This function doesn't perform detection, it merely reads the result from a previous call to <a href="#">simHandleProximitySensor</a> ( <code>simHandleProximitySensor</code> is called in the default main script). See also <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,boolean detectionState,array detectedPoint,number detectedObjectHandle,array detectedSurfaceNormalVector=simxReadProximitySensor(number clientID,number sensorHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>sensorHandle</b> : handle of the proximity sensor <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a> <b>detectionState</b> : the detection state. <b>detectedPoint</b> : the detected point coordinates (relative to the sensor reference frame). <b>detectedObjectHandle</b> : the handle of the detected object. <b>detectedSurfaceNormalVector</b> : the normal vector (normalized) of the detected surface. Relative to the sensor reference frame.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxReadStream

Description	Gets the value of a string signal, then clears it. Useful to retrieve continuous data from the server. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a> . See also <a href="#">simxWriteStringStream</a> .
Python synopsis	number errorCode,string signalValue=simxReadStream(number clientID,string signalName,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls). <code>simx_opmode_oneshot_wait</code> is forbidden. Use a construction like following in order to continuously exchange data with V-REP:  Remote API client side:  <pre>'''Initialization phase:''' err,signal=vrep.simxReadStream(     clientID,"toClient",uiHandle,vrep.simx_opmode_streaming)  '''while we are connected:''' while vrep.simxGetConnectionId(clientID) != -1:     err,signal=vrep.simxReadStream(         clientID,"toClient",uiHandle,vrep.simx_opmode_buffer)     if (err==vrep.simx_return_ok):         '''Data produced by the child script was retrieved! Send it back to the child script:'''         vrep.simxWriteStringStream(clientID,"fromClient",signal,vrep.simx_opmode_oneshot)</pre> Server side (V-REP), from a non-threaded child script:  <pre>if (sim_call_type==sim_childscriptcall_initialization) then     -- initialization phase:     i=0     lastReceived=-1 end  if (sim_call_type==sim_childscriptcall_actuation) then     -- First send a stream of integers that count up:     dat=simGetStringSignal('toClient')     if not dat then         dat=''     end end</pre>

	<pre> end dat=dat..simPackInts({i}) i=i+1 simSetStringSignal('toClient',dat)  -- Here receive the integer stream in return and check if each number is correct: dat=simGetStringSignal('fromClient') if dat then     simClearStringSignal('fromClient')     dat=simUnpackInts(dat)     for j=1,#dat,1 do         if (dat[j]~=lastReceived+1) then             print('Error')         else             io.write('.')             lastReceived=dat[j]         end     end end end end end </pre>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>signalValue:</b> the value of the signal.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxReadVisionSensor (regular API equivalent: [simReadVisionSensor](#))

Description	Reads the state of a vision sensor. This function doesn't perform detection, it merely reads the result from a previous call to <a href="#">simHandleVisionSensor</a> ( <a href="#">simHandleVisionSensor</a> is called in the default main script). See also <a href="#">simxGetVisionSensorImage</a> and <a href="#">simxGetObjectGroupData</a> .
Python synopsis	number errorCode,boolean detectionState,array auxPackets=simxReadVisionSensor(number clientID,number sensorHandle,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>sensorHandle:</b> handle of the vision sensor <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <a href="#">simx_opmode_streaming</a> (the first call) and <a href="#">simx_opmode_buffer</a> (the following calls)
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a> <b>detectionState:</b> the detection state (i.e. the trigger state). <b>auxPackets:</b> packets containing auxiliary values returned from the <a href="#">applied filters</a> . By default V-REP returns one packet of 15 auxiliary values:the minimum of {intensity, red, green, blue, depth value}, the maximum of {intensity, red, green, blue, depth value}, and the average of {intensity, red, green, blue, depth value}. If additional filter components return values, then they will be appended as packets after the first packet.
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxReleaseBuffer (regular API equivalent: [simReleaseBuffer](#))

Description	Releases a buffer previously created with <a href="#">simxCreateBuffer</a> or a buffer returned by a remote API function. This is a remote API helper function.
Python synopsis	simxReleaseBuffer(charPointer buffer)
Python parameters	<b>buffer:</b> buffer to be released
Python return values	none
Other languages	<a href="#">C/C++</a> , <a href="#">Matlab</a>

### simxRemoveModel (regular API equivalent: [simRemoveModel](#))

Description	Removes a model from the scene. See also <a href="#">simxRemoveObject</a> .
Python synopsis	number errorCode=simxRemoveModel(number clientID,number objectHandle,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle:</b> handle of the model to remove (object should be flagged as model base). <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <a href="#">simx_opmode_oneshot</a> (or <a href="#">simx_opmode_oneshot_wait</a> )
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxRemoveObject (regular API equivalent: [simRemoveObject](#))

Description	Removes a scene object. See also <a href="#">simxRemoveModel</a> .
Python synopsis	number errorCode=simxRemoveObject(number clientID,number objectHandle,number operationMode)
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle:</b> handle of the object to remove <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <a href="#">simx_opmode_oneshot</a> (or <a href="#">simx_opmode_oneshot_wait</a> )
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxRemoveUI (regular API equivalent: simRemoveUI)**

Description	Removes a custom user interface.
Python synopsis	number errorCode=simxRemoveUI(number clientID,number uiHandle,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiHandle</b> : handle of the custom user interface <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code> (or <code>simx_opmode_oneshot_wait</code> )
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSetArrayParameter (regular API equivalent: simSetArrayParameter)**

Description	Sets 3 values of an <a href="#">array parameter</a> . See also <a href="#">simxGetArrayParameter</a> , <a href="#">simxSetBooleanParameter</a> , <a href="#">simxSetIntegerParameter</a> and <a href="#">simxSetFloatingParameter</a> .
Python synopsis	number errorCode=simxSetArrayParameter(number clientID,number paramIdentifier,array paramValues,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : an <a href="#">array parameter identifier</a> <b>paramValues</b> : the array containing the 3 values to set <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSetBooleanParameter (regular API equivalent: simSetBooleanParameter)**

Description	Sets a <a href="#">boolean parameter</a> . See also <a href="#">simxGetBooleanParameter</a> , <a href="#">simxSetIntegerParameter</a> , <a href="#">simxSetArrayParameter</a> and <a href="#">simxSetFloatingParameter</a> .
Python synopsis	number errorCode=simxSetBooleanParameter(number clientID,number paramIdentifier,boolean paramValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : a <a href="#">Boolean parameter identifier</a> <b>paramValue</b> : the parameter value <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSetFloatingParameter (regular API equivalent: simSetFloatingParameter)**

Description	Sets a <a href="#">floating point parameter</a> . See also <a href="#">simxGetFloatingParameter</a> , <a href="#">simxSetBooleanParameter</a> , <a href="#">simxSetArrayParameter</a> and <a href="#">simxSetIntegerParameter</a> .
Python synopsis	number errorCode=simxSetFloatingParameter(number clientID,number paramIdentifier,number paramValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : a <a href="#">floating parameter identifier</a> <b>paramValue</b> : the parameter value <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSetFloatSignal (regular API equivalent: simSetFloatSignal)**

Description	Sets the value of a float signal. If that signal is not yet present, it is added. See also <a href="#">simxGetFloatSignal</a> , <a href="#">simxClearFloatSignal</a> , <a href="#">simxSetIntegerSignal</a> and <a href="#">simxSetStringSignal</a> .
Python synopsis	number errorCode=simxSetFloatSignal(number clientID,string signalName,number signalValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>signalValue</b> : value of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSetIntegerParameter (regular API equivalent: simSetIntegerParameter)**

Description	Sets an <a href="#">integer parameter</a> . See also <a href="#">simxGetIntegerParameter</a> , <a href="#">simxSetBooleanParameter</a> , <a href="#">simxSetArrayParameter</a> and <a href="#">simxSetFloatingParameter</a> .
Python synopsis	number errorCode=simxSetIntegerParameter(number clientID,number paramIdentifier,number paramValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>paramIdentifier</b> : an <a href="#">integer parameter identifier</a> <b>paramValue</b> : the parameter value <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetIntegerSignal (regular API equivalent: [simSetIntegerSignal](#))

Description	Sets the value of an integer signal. If that signal is not yet present, it is added. See also <a href="#">simxGetIntegerSignal</a> , <a href="#">simxClearIntegerSignal</a> , <a href="#">simxSetFloatSignal</a> and <a href="#">simxSetStringSignal</a> .
Python synopsis	number errorCode=simxSetIntegerSignal(number clientID,string signalName,number signalValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>signalValue</b> : value of the signal <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetJointForce (regular API equivalent: [simSetJointForce](#))

Description	Sets the maximum force or torque that a joint can exert. This function has no effect when the joint is not dynamically enabled, or when it is a spherical joint. See also <a href="#">simxGetJointForce</a> .
Python synopsis	number errorCode=simxSetJointForce(number clientID,number jointHandle,number force,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>force</b> : the maximum force or torque that the joint can exert <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetJointPosition (regular API equivalent: [simSetJointPosition](#))

Description	Sets the intrinsic position of a joint. May have no effect depending on the joint mode. This function cannot be used with spherical joints (use <a href="#">simxSetSphericalJointMatrix</a> instead). If you want to set several joints that should be applied at the exact same time on the V-REP side, then use <a href="#">simxPauseCommunication</a> . See also <a href="#">simxGetJointPosition</a> and <a href="#">simxSetJointTargetPosition</a> .
Python synopsis	number errorCode=simxSetJointPosition(number clientID,number jointHandle,number position,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>position</b> : position of the joint (angular or linear value depending on the joint type) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_oneshot</code> or <code>simx_opmode_streaming</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetJointTargetPosition (regular API equivalent: [simSetJointTargetPosition](#))

Description	Sets the target position of a joint if the joint is in torque/force mode (also make sure that the joint's motor and position control are enabled). See also <a href="#">simxSetJointPosition</a> .
Python synopsis	number errorCode=simxSetJointTargetPosition(number clientID,number jointHandle,number targetPosition,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>targetPosition</b> : target position of the joint (angular or linear value depending on the joint type) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_oneshot</code> or <code>simx_opmode_streaming</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetJointTargetVelocity (regular API equivalent: [simSetJointTargetVelocity](#))

Description	Sets the intrinsic target velocity of a non-spherical joint. This command makes only sense when the joint mode is: (a) motion mode: the joint's motion handling feature must be enabled ( <a href="#">simHandleJoint</a> must be called (is called by default in the main script), and the joint motion properties must be set in the joint settings dialog), (b) torque/force mode: the dynamics functionality and the joint motor have to be enabled (position control should however be disabled)
Python synopsis	number errorCode=simxSetJointTargetVelocity(number clientID,number jointHandle,number targetVelocity,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle</b> : handle of the joint <b>targetVelocity</b> : target velocity of the joint (linear or angular velocity depending on the joint-type) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_oneshot</code> or <code>simx_opmode_streaming</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetModelProperty (regular API equivalent: [simSetModelProperty](#))

Description	Sets the properties of a model. See also <a href="#">simxGetModelProperty</a> .
Python synopsis	number errorCode=simxSetModelProperty(number clientID,number objectHandle,number prop,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>prop</b> : a <a href="#">model property value</a> <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectFloatParameter (regular API equivalent: [simSetObjectFloatParameter](#))

Description	Sets a floating-point parameter of an object. See also <a href="#">simxGetObjectFloatParameter</a> and <a href="#">simxSetObjectIntParameter</a> .
Python synopsis	number errorCode=simxSetObjectFloatParameter(number clientID,number objectHandle,number parameterID,number parameterValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>parameterID</b> : identifier of the parameter to set. See the <a href="#">list of all possible object parameter identifiers</a> <b>parameterValue</b> : the desired value of the parameter <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectIntParameter (regular API equivalent: [simSetObjectIntParameter](#))

Description	Sets an integer parameter of an object. See also <a href="#">simxGetObjectIntParameter</a> and <a href="#">simxSetObjectFloatParameter</a> .
Python synopsis	number errorCode=simxSetObjectIntParameter(number clientID,number objectHandle,number parameterID,number parameterValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>parameterID</b> : identifier of the parameter to set. See the <a href="#">list of all possible object parameter identifiers</a> <b>parameterValue</b> : the desired value of the parameter <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectOrientation (regular API equivalent: [simSetObjectOrientation](#))

Description	Sets the orientation ( <a href="#">Euler angles</a> ) of an object. Dynamically simulated objects will implicitly be reset before the command is applied (i.e. similar to calling <a href="#">simResetDynamicObject</a> just before). See also <a href="#">simxGetObjectOrientation</a> and <a href="#">simxSetObjectPosition</a> .
Python synopsis	number errorCode=simxSetObjectOrientation(number clientID,number objectHandle,number relativeToObjectHandle,array eulerAngles,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle</b> : handle of the object <b>relativeToObjectHandle</b> : indicates relative to which reference frame the orientation is specified. Specify -1 to set the absolute orientation, <code>sim_handle_parent</code> to set the orientation relative to the object's parent, or an object handle relative to whose reference frame the orientation is specified. <b>eulerAngles</b> : Euler angles (alpha, beta and gamma)

	<b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectParent (regular API equivalent: [simSetObjectParent](#))

Description	Sets an object's parent object. See also <a href="#">simxGetObjectParent</a> .
Python synopsis	<code>number errorCode=simxSetObjectParent(number clientID,number objectHandle,number parentObject,boolean keepInPlace,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle:</b> handle of the object that will become child of the parent object. Can be combined with <a href="#">sim_handleflag_assembly</a> , if the two objects can be assembled via a predefined assembly transformation (refer to the <b>assembling</b> option in the <a href="#">object common properties</a> ). In that case, <b>parentObject</b> can't be -1, and <b>keepInPlace</b> should be set to false. <b>parentObject:</b> handle of the object that will become parent, or -1 if the object should become parentless <b>keepInPlace:</b> indicates whether the object's absolute position and orientation should stay same <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code> or <code>simx_opmode_oneshot_wait</code> depending on the intent
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectPosition (regular API equivalent: [simSetObjectPosition](#))

Description	Sets the position of an object. Dynamically simulated objects will implicitly be reset before the command is applied (i.e. similar to calling <a href="#">simResetDynamicObject</a> just before). See also <a href="#">simxGetObjectPosition</a> and <a href="#">simxSetObjectOrientation</a> .
Python synopsis	<code>number errorCode=simxSetObjectPosition(number clientID,number objectHandle,number relativeToObjectHandle,array position,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>objectHandle:</b> handle of the object <b>relativeToObjectHandle:</b> indicates relative to which reference frame the position is specified. Specify -1 to set the absolute position, <code>sim_handle_parent</code> to set the position relative to the object's parent, or an object handle relative to whose reference frame the position is specified. <b>position:</b> the position values (x, y and z) <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetObjectSelection

Description	Sets the selection state for objects. See also <a href="#">simxGetObjectSelection</a> .
Python synopsis	<code>number errorCode=simxSetObjectSelection(number clientID,array objectHandles,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>objectHandles:</b> an array of object handles <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code> or <code>simx_opmode_oneshot_wait</code> depending on the intent.
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetSphericalJointMatrix (regular API equivalent: [simSetSphericalJointMatrix](#))

Description	Sets the intrinsic orientation matrix of a spherical joint object. This function cannot be used with non-spherical joints (use <a href="#">simxSetJointPosition</a> instead). See also <a href="#">simxGetJointMatrix</a> ..
Python synopsis	<code>number errorCode=simxSetSphericalJointMatrix(number clientID,number jointHandle,array matrix,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>jointHandle:</b> handle of the joint <b>matrix:</b> 12 values. See the regular API equivalent function for details <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function are <code>simx_opmode_oneshot</code> or <code>simx_opmode_streaming</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetStringSignal (regular API equivalent: [simSetStringSignal](#))

Description	Sets the value of a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and
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	<a href="#">simxUnpackFloats</a> . See also <a href="#">simxAppendStringSignal</a> , <a href="#">simxGetStringSignal</a> , <a href="#">simxClearStringSignal</a> , <a href="#">simxSetIntegerSignal</a> and <a href="#">simxSetFloatSignal</a> .
Python synopsis	number errorCode=simxSetStringSignal(number clientID,string signalName,string signalValue,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>signalValue</b> : value of the signal (which may contain any value, including embedded zeros) <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetUIButtonLabel (regular API equivalent: [simSetUIButtonLabel](#))

Description	Sets the up-state and down-state labels of a custom user interface button.
Python synopsis	number errorCode=simxSetUIButtonLabel(number clientID,number uiHandle,number uiButtonID,string upStateLabel,string downStateLabel,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiHandle</b> : handle of the custom user interface <b>uiButtonID</b> : handle (or ID) of the custom user interface button <b>upStateLabel</b> : string containing the label of the button when it is up. <b>downStateLabel</b> : string containing the label of the button when it is down.. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetUIButtonProperty (regular API equivalent: [simSetUIButtonProperty](#))

Description	Sets the properties of a custom user interface button. See also <a href="#">simxGetUIButtonProperty</a> .
Python synopsis	number errorCode=simxSetUIButtonProperty(number clientID,number uiHandle,number uiButtonID,number prop,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiHandle</b> : handle of the custom user interface <b>uiButtonID</b> : handle (or ID) of the custom user interface button <b>prop</b> : a <a href="#">button property value</a> . <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetUISlider (regular API equivalent: [simSetUISlider](#))

Description	Sets the slider position of a custom user interface button (must be a slider-type button). See also <a href="#">simxGetUISlider</a> .
Python synopsis	number errorCode=simxSetUISlider(number clientID,number uiHandle,number uiButtonID,number position,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>uiHandle</b> : handle of the custom user interface <b>uiButtonID</b> : id of the button (slider) in the custom user interface <b>position</b> : slider position. valid values are between 0 and 1000 <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

#### simxSetVisionSensorImage (regular API equivalent: [simSetVisionSensorImage](#))

Description	Sets the image of a vision sensor (and applies any image processing filter if specified in the vision sensor dialog). Make sure the vision sensor is flagged as <b>use external image</b> . The "regular" use of this function is to first read the data from a vision sensor with <a href="#">simxGetVisionSensorImage</a> , do some custom filtering, then write the modified image to a passive vision sensor. The alternate use of this function is to display textures, video images, etc. by using a vision sensor object (without however making use of the vision sensor functionality), since a vision sensor can be "looked through" like camera objects.
Python synopsis	number errorCode=simxSetVisionSensorImage(number clientID,number sensorHandle,array image,number options,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>sensorHandle</b> : handle of the vision sensor <b>image</b> : image data <b>options</b> : image options, bit-coded: bit0 set: each image pixel is a byte (greyscale image), otherwise each image pixel is a rgb byte-triplet

	<b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxStart**

Description	Starts a communication thread with the server (i.e. V-REP). A same client may start several communication threads (but only one communication thread for a given IP and port). This should be the very first remote API function called on the client side. Make sure to start an appropriate remote API server service on the server side, that will wait for a connection. See also <a href="#">simxFinish</a> . This is a remote API helper function.
Python synopsis	<code>number clientID=simxStart(string connectionAddress,number connectionPort,boolean waitUntilConnected,boolean doNotReconnectOnceDisconnected,number timeOutInMs,number commThreadCycleInMs)</code>
Python parameters	<b>connectionAddress:</b> the ip address where the server is located (i.e. V-REP) <b>connectionPort:</b> the port number where to connect <b>waitUntilConnected:</b> if True, then the function blocks until connected (or timed out). <b>doNotReconnectOnceDisconnected:</b> if True, then the communication thread will not attempt a second connection if a connection was lost. <b>timeOutInMs:</b> connection time-out in milliseconds (for the first connection). <b>commThreadCycleInMs:</b> indicates how often data packets are sent back and forth. Reducing this number improves responsiveness, and a default value of 5 is recommended.
Python return values	<b>clientID:</b> the client ID, or -1 if the connection to the server was not possible (i.e. a timeout was reached). A call to <code>simxStart</code> should always be followed at the end with a call to <a href="#">simxFinish</a> if <code>simxStart</code> didn't return -1
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxStartSimulation (regular API equivalent: simStartSimulation)**

Description	Requests a start of a simulation (or a resume of a paused simulation). This function is only executed by <a href="#">continuous remote API server services</a> . See also <a href="#">simxPauseSimulation</a> and <a href="#">simxStopSimulation</a> .
Python synopsis	<code>number errorCode=simxStartSimulation(number clientID,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code> .
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxStopSimulation (regular API equivalent: simStopSimulation)**

Description	Requests a stop of the running simulation. See also <a href="#">simxStartSimulation</a> and <a href="#">simxPauseSimulation</a> .
Python synopsis	<code>number errorCode=simxStopSimulation(number clientID,number operationMode)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>operationMode:</b> a <a href="#">remote API function operation mode</a> . Recommended operation modes for this function is <code>simx_opmode_oneshot</code> .
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSynchronous**

Description	Enables or disables the synchronous operation mode for the remote API server service that the client is connected to. The function is blocking. While in synchronous operation mode, the client application is in charge of triggering the next simulation step. Only pre-enabled remote API server services will successfully execute this function. See also <a href="#">simxSynchronousTrigger</a> and the <a href="#">remote API overview</a> . This is a remote API helper function.
Python synopsis	<code>number errorCode=simxSynchronous(number clientID,boolean enable)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> . <b>enable:</b> the enable state of the synchronous operation
Python return values	<b>errorCode:</b> a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

**simxSynchronousTrigger**

Description	Sends a synchronization trigger signal to the server. The function is blocking. The server needs to be previously enabled for synchronous operation via the <a href="#">simxSynchronous</a> function. The trigger signal will inform V-REP to execute the next simulation step (i.e. to call <a href="#">simHandleMainScript</a> ). While in synchronous operation mode, the client application is in charge of triggering the next simulation step, otherwise simulation will stall. See also the <a href="#">remote API overview</a> . This is a remote API helper function.
Python synopsis	<code>number errorCode=simxSynchronousTrigger(number clientID)</code>
Python parameters	<b>clientID:</b> the client ID. refer to <a href="#">simxStart</a> .



Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxTransferFile

Description	Allows transferring a file from the client to the server. This function is used by several other functions internally (e.g. <a href="#">simxLoadModel</a> ). See also <a href="#">simxEraseFile</a> . This is a remote API helper function.
Python synopsis	number errorCode=simxTransferFile(number clientID,string filePathAndName,string fileName_serverSide,number timeOut,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>filePathAndName</b> : the local file name and path (i.e. on the client side) <b>fileName_serverSide</b> : a file name under which the transferred file will be saved on the server side. For now, do not specify a path (the file will be saved in the remote API plugin directory) <b>timeOut</b> : a timeout value in milliseconds <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot_wait</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxWriteStringStream

Description	Appends a string to a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to <a href="#">simxPackInts</a> , <a href="#">simxPackFloats</a> , <a href="#">simxUnpackInts</a> and <a href="#">simxUnpackFloats</a> . See also <a href="#">simxReadStringStream</a> .
Python synopsis	number errorCode=simxWriteStringStream(number clientID,string signalName,string signalValueToAppend,number operationMode)
Python parameters	<b>clientID</b> : the client ID. refer to <a href="#">simxStart</a> . <b>signalName</b> : name of the signal <b>signalValueToAppend</b> : value to append to the signal. That value may contain any value, including embedded zeros. <b>operationMode</b> : a <a href="#">remote API function operation mode</a> . Recommended operation mode for this function is <code>simx_opmode_oneshot</code>
Python return values	<b>errorCode</b> : a <a href="#">remote API function return code</a>
Other languages	<a href="#">C/C++</a> , <a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxUnpackFloats

Description	Unpacks a string into an array of floats. This is a remote API helper function. See also <a href="#">simxPackFloats</a> and <a href="#">simxUnpackInts</a> .
Python synopsis	array floatValues=simxUnpackFloats(string packedData)
Python parameters	<b>packedData</b> : a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Python return values	<b>floatValues</b> : an array of numbers that were unpacked as floats
Other languages	<a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>

### simxUnpackInts

Description	Unpacks a string into an array of integers. This is a remote API helper function. See also <a href="#">simxPackInts</a> and <a href="#">simxUnpackFloats</a> .
Python synopsis	array intValue=simxUnpackInts(string packedData)
Python parameters	<b>packedData</b> : a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Python return values	<b>intValue</b> : an array of numbers that were unpacked as integers
Other languages	<a href="#">Java</a> , <a href="#">Matlab</a> , <a href="#">Octave</a> , <a href="#">Urbi</a>